

AHM5 RANGE

CANOPEN ABSOLUTE SINGLE TURN ENCODERS



Features

AHM5 characterizes itself by its strong robustness of the mechanical and electro-magnetic parts:

- Application Fields: agriculture, construction, forestry vehicles, medical applications, solar panels...
- Magnetic technology, contactless.
- Strong robustness with its reinforced bearing block and its stopped bearings.
- Available resolution up to 12 bits.
- Universal supply from 5 to 30Vdc.
- Also Available: analog, PWM, and SSI outputs.
- Available in Options : Extended temperature range (up to -40..+125°C), IP67/IP69K...



Mechanical

Material	Shaft: Stainless Steel, Cover: Zinc Alloy, Body: Aluminium						
Bearings	6 000 series						
Maximal Loads	Axial: 100 N, Radial: 200 N						
Shaft Inertia	$\leq 0.4.10^{-6} \text{ kg.m}^2$						
Torque	≤7.10 ⁻³ N.m						
Nominal Max. Speed	6 000 min ⁻¹						
Encoder Weight (Approx.)	0,300 kg						
Isolation	500 Veff						
EMC	EN 61000-6-4, EN 61000-6-2						
Operating Temperature	- 40 + 85 °C (T° encoder)						
Storage Temperature	- 40 + 85 °C						
Protection	IP 65						
Shocks (EN60068-2-27)	≤ 2000m.s ⁻² (during 6 ms)						
Vibrations (EN60068-2-6)	≤ 200m.s ⁻² (55 2 000 Hz)						
Theoretical Mechanical Lifetime	10º Turns (F _{axial} / F _{radial})						
100 N / 200 N	3.10 ⁹ Turns						

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Electrical

Power Supply	5-30Vdc
Comsumption Without Load	< 40mA (at 24Vdc)
Resolution	4096 (2 ¹²)
Accuracy	± 0.3 % (on 360°)
Repeatability	± 0.1 % (on 360°)
Introduction	<1s
Refresh Rate	< 400 s



TECHNICAL SPECIFICATIONS

Programmable Parameters

Resolution: Defines the resolution per revolution (0 à 4 096).

Transmission Speed: Programmable from 10kBaud (1 000m) to 1 Mbaud (25 m); value per default: 20 Kbaud.

Address: Defines the software address of the encoder on the bus (1 à 127, Value per default : id = 1).

Direction: Defines the direction of count of the encoder.

RAX: Define the value of the current position (stationnary shaft).

Cames: High and low limits.

Communication Modes

Encoder Configuration: Reading/Writing of the encoder objects dictionnary (SDO mode). 3 modes are available to interrogate the encoder position/speed:

CYCLIC Mode: the encoder transmits its position in an asynchronous manner. The frequency of the transmission is defined

by the programmable cyclic timer register from 0 to 65 535 ms,

SYNCHRO Mode: the encoder transmits its position on a synchronous demand by the master.

POOLING Mode (Answer to a RTR signal): the encoder only answers to a request.

CANopen Connection, Cable + DB9 Connector

		N.C.	CAN LOW	CAN GND	N.C.	N.C.	0V	CAN HIGH	N.C.	5/30Vdc	Ground
ВВ	PVC Cable + DB9	1	2	3	4	5	6	7	8	9	General Shielding
ВС	M23 12 Pinouts	1	2	3	4	5	10	7	6, 8, 9, 11	12	Connector Body

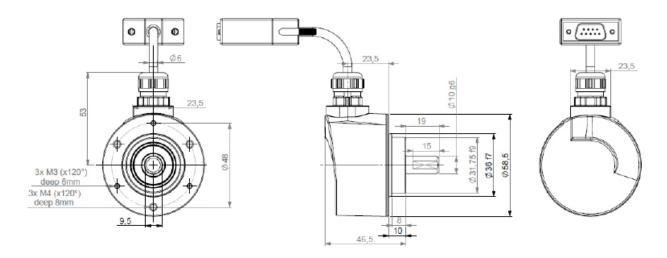
Note: Refer to the bus standards for the maximal derivation length.



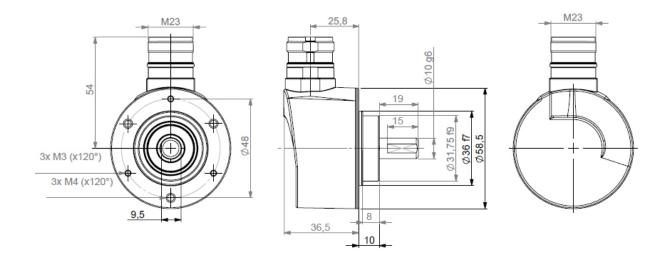


All dimensions are in millimeters.

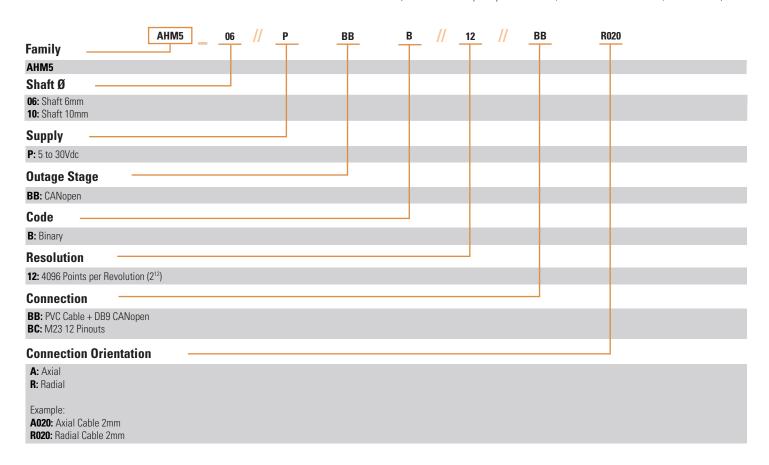
AHM5_10 with BB Connection (Radial Cable)



AHM5_10 with BC Connection (Radial M23)



(Contact the factory for special versions, ex: stainless steel version, connections...)





AGENCY APPROVALS & CERTIFICATIONS



Made in France

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